Example code at:
https://github.com/SuperDroidRobots/Encoder-Buffer-Breakout

Note: In case encoders are counting the opposite direction you can swap A and B in that channel.

Motor with encoder Pin Out:
- Purple : Hall Sensor B
- Blue : Hall Sensor A
- Brown : Hall Sensor Vcc
- Green : Hall Sensor GND
- Red : +Motor
- Black : -Motor

Note: Pull up resistors solder jumpers. If you are using encoders and they require pull ups resistors these need to be bridge. Unsolder if no you don’t need pull up resistors

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IG32, IG42, IG52 Electric Motors
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