

Notes:

- Its OK to connect ground to the chassis, however use wire to connect all ground terminations (same size as +V)
- Ensure all electronics are electrically isolated from chassis
- (A) Mount Mobile Transceiver in rear of robot and run whip antenna out the back of the robot
- (B) Must Solder wires onto back of OOPic-R board to access the TTL lines of the OOPic see www.superdroidrobots.com/product_info/RF.htm
- (C) connect to 5V TTL Header
- (D) Jumper right onto OOPic Pins
Any digital I/O pin can be used for direction
direction I/O pins selected are close to PWMs

