Notes:
1. It's OK to connect ground to the chassis, however use wire to connect all ground terminations (same size as +24V)
2. Ensure all electronics are electrically isolated from chassis
3. Mount Mobile Transceiver in rear of robot and run whip antenna out the back of the robot
4. Must solder wires onto back of OOPic-R board to access the TTL lines of the OOPic
5. Connect to 5V TTL Header
6. Jumper right onto OOPic Pins
   Any digital I/O pin can be used for direction
   direction I/O pins selected are close to PMs

SuperDroid Robots Inc.
MD03, OOPic-R & RF Schematic

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